

# **Product Data Sheet**

Range:

Title: 8mm Linear Resonant Actuator

Type: Undefined Model:

C08-005

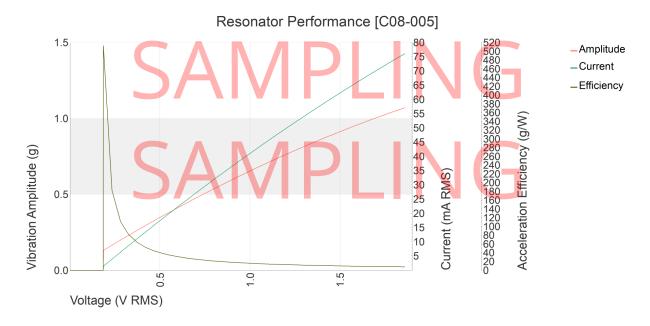
8mm Linear Resonant Actuator 3mm Type

Shown on 6mm Isometric Grid



KEY FEATURES	
Body Diameter	8 mm [+/- 0.1]
Body Length	3.3 mm [+/- 0.15]
Rated Voltage (RMS)	1.8 V
Rated Vibration Frequency	235 Hz
Typical Rated Operating Current	75 mA
Typical Norm. Amplitude	1.28 G

#### TYPICAL DC MOTOR PERFORMANCE CHARACTERISTICS



#### **ORDERING INFORMATION**

The model number fully defines the model, variant and additional features of the product. Please quote this number when ordering. For stocked types, testing and evaluation samples can be ordered directly through our online store.

FIND OUT HOW THIS PART COULD MEET YOUR SPECIFICATIONS



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#### **DESIGN FOR APPLICATION CASE STUDIES**



# ENCAPSULATED VIBRATION MOTOR FOR A CPR TRAINING DUMMY

- Low volume, high value manufacturing
- Custom CNC machined enclosure
- Optimised haptic performance
- Custom PCB including EMI filters
- Part no. 334-401.001



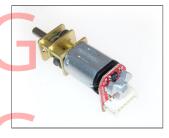
#### VIBRATION MOTOR HIGHLY OPTIMISED FOR RUGGEDISED FIRE AND POLICE EMERGENCY RADIOS

- High volume production
- Optimised for emergency services application
- Ruggedised design with custom rubber 'suspension' cover
- Custom PCB with spring legs for simplified production assembly times
- Part no. 308-104.001



# PRECISION SPEED AND TORQUE CONTROLLED SERVO WITH INTEGRATED TUNABLE PID LOOP FOR SINGLE-USE SCIENTIFIC INSTRUMENT.

- Medium volume, high value assembly
- Proprietary PID controller converts cost-effective motor design into a precision servo
- Adapted control software including digital IO (to customer's specification)
- Part no. 132-100.001



# CUSTOMISED PRECISION GEAR MOTOR WITH ROBUST OPTICAL ENCODER

- High volume production
- Application specific output shaft
- Tailored motor performance curves
- Rear motor shaft with noise resistant optical encoder
- Part no. 212-116.001



PARAMETER	CONDITIONS	SPECIFICATION
Body Diameter	Max body diameter or max face dimension where non-circular	8 mm [+/- 0.1]
Body Length	Excl. shafts, leads and terminals	3.3 mm [+/- 0.15]
Unit Weight		0.95 g

#### **LEADS & CONNECTORS SPECIFICATION**

PARAMETER	CONDITIONS	SPECIFICATION
Lead Length	Lead lengths defined as total length or between motor and connector	100 mm [+/- 2]
Lead Strip Length		1.5 mm [+/- 0.5]
Lead Wire Gauge	UL3302	32 AWG
Lead Configuration		Straight

#### **OPERATIONAL SPECIFICATION**

PARAMETER	CONDITIONS	SPECIFICATION
Max. Start Voltage	Certified starting voltage. Sinusoidal waveform at Rated Vibration Frequency. Voltage specified as RMS	0.5 V
Rated Voltage (RMS)	Sinusoidal waveform at Rated Vibration Frequency. Voltage specified as RMS	1.8 V
Auto-Resonance Driving	Performance with drivers using auto-resonance is greatly influenced by the application. 30% (typ.) voltage reduction in driving voltage and case-by-case validation is required.	
Rated Vibration Frequency		235 Hz
Max. Rated Operating Current	RMS Value. At rated voltage using the inertial test load	102 mA
Max. Operating Voltage	Sinusoidal waveform at Rated Vibration Frequency. Voltage specified as RMS	1.85 V
Rated Inertial Test Load	Mass of rated load standard test sled	100 g
Min. Insulation Resistance	At 50V DC between motor terminal and case	1 MOhm
Min. Vibration Amplitude	Peak-to-peak value at rated voltage using the inertial test load	0.61 G
Resonant Frequency		233 Hz [+/- 8]

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**Important:** The characteristics of the motor is the typical operating parameters of the product. The data herein offers design guidance information only and supplied batches are validated for conformity against the specifications on the previous page.

#### TYPICAL PERFORMANCE CHARACTERISTICS

PARAMETER	CONDITIONS	SPECIFICATION
Typical Rated Operating Current	RMS Value. At rated voltage using the inertial test load	75 mA
Typical Vibration Amplitude	Peak-to-peak value at rated voltage using the inertial test load	1.02 G
Typical Start Voltage	Sinusoidal waveform at Rated Vibration Frequency. Voltage specified as RMS	0.17 V
Typical Vibration Efficiency	At rated voltage using the inertial test load	10.7 G/W
Typical Norm. Amplitude	Peak-to-peak vibration amplitude normalised by the inertial test load at rated voltage	1.28 G
Typical Terminal Resistance		21 Ohm
Typical Terminal Inductance		112.6 uH

#### TYPICAL HAPTIC CHARACTERISTICS

PARAMETER	CONDITIONS	SPECIFICATION
Typical Lag Time	At rated voltage using the inertial test load	12 ms
Typical Rise Time	At rated voltage using the inertial test load	33 ms
Typical Stop Time	At rated voltage using the inertial test load	123 ms

## ENVIRONMENTAL CHARACTERISTICS

PARAMETER	CONDITIONS	SPECIFICATION
Max. Operating Temp.		70 Deg.C
Min. Operating Temp.	$\Delta MPIIM$	-25 Deg.C
Max. Storage & Transportation Temp.		85 Deg.C
Min. Storage & Transportation Temp.		-40 Deg.C

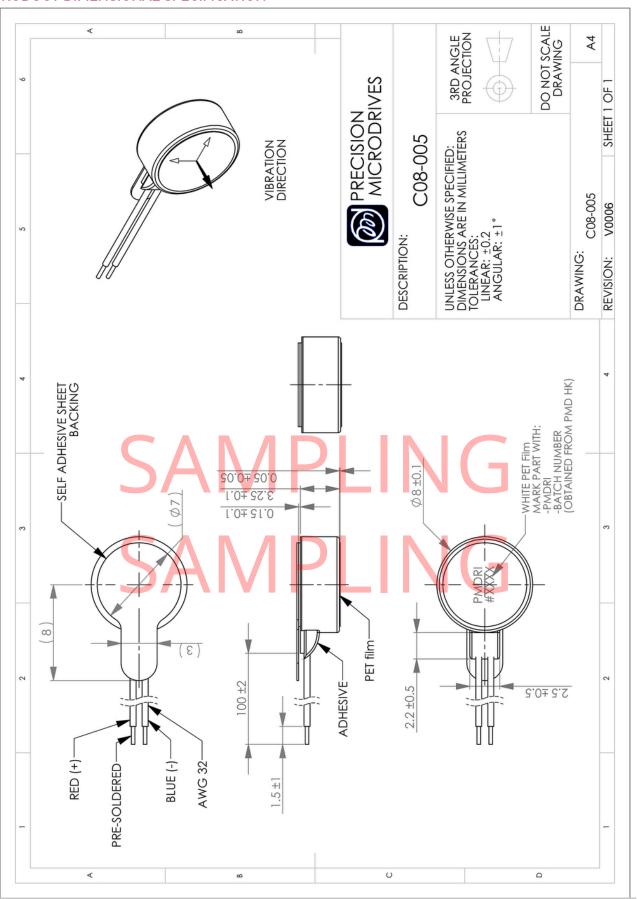
#### TYPICAL PACKING CONDITIONS

PARAMETER	CONDITIONS	SPECIFICATION
Carton Type		Boxed Trays

FIND OUT HOW THIS PART COULD MEET YOUR SPECIFICATIONS



#### PRODUCT DIMENSIONAL SPECIFICATION



FIND OUT HOW THIS PART COULD MEET YOUR SPECIFICATIONS



#### **Application Notice**

This device may be driven using an LRA driver IC such as the TI DRV2605L or TI DRV2625. The performance of such drivers is greatly influenced by the application - particularly in Auto-Resonance modes, which typically require the LRA to be mounted to a large mass for optimal performance. The LRA's performance should be validated in the product during the design phase, and a reduction in driving voltage may be necessary to prevent damage to the LRA and ensure its longevity. In Auto-Resonance mode, a reduction in driving voltage of 30% is typically required to achieve optimal performance and

# SAMPLIN SAMPLING



#### **HOW TO ORDER**

Call or email us with your order requirements at:

Email: enquiries@precisionmicrodrives.com

Phone: **+44 (0) 1932 252482** 

Please quote the full part number when ordering or making an enquiry. Some products can be ordered in smaller volumes directly from our website: **www.precisionmicrodrives.com** 

#### DATASHEET REVISION AND VERSION NUMBERING

We aim to provide ou customer with the most detailed product information available. Sometimes changes are necessary, and these will be controlled by our engineering change request and notification process. To track datasheet versions we use both a 'production revision number' and a 'document version number'. These can be found at the bottom of every page. Inc some cases, such as documentation errors, the document version number can increase without triggering a product revision.

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- 1. Life support devices or systems are devices or systems which,
  - 1.1. are intended for surgical implant into the body, or
  - 1.2. support or sustain life, and whose failure to perform when properly used in accordance with instructions for use provided in the labeling, can be reasonably expected to result in a significant injury to the user or a third party.
- 2. A critical component is any component of a life support device or any other system or machine whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

#### BATCH NUMBERING, MANUFACTURING, TRACEABILITY AND LABELLING

Every part of manufactured by Precision Microdrives is at minimum identified and traced via a batch number. Where physically practical, we try to make each part with a batch number. In addition, some parts carry a lot code or barcode serial numbers. If traceability is a core requirement for your purchase, let us know and we'll outline the production options for you.

#### STANDARD QUALITY CONTROLS AND ISO 9001

Precision quality control is one of our 3 key competitive advantages. All motors that we produce undergo 100% line inspection followed by strict and detailed batch sample testing in accordance with ISO 2859. All of the processes operated at Precision Microdrives are managed within our ISO 9001 quality system.



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